

## B. Space group

### 1. The 230 crystallographic 3D space groups

(You may find detailed information in Wikipedia, the free encyclopedia)

Symmetry elements in space group

- (1) Point group
- (2) Translation symmetry + point group

Translational symmetry operations

### A Symbol of symmetry planes

Symbol	Symmetry plane	Graphic symbol		Nature of glide translation
		Normal to plane of projection	Parallel to plane of projection	
m	Reflection plane (mirror)			None
a, b	Axial glide plane			a/2 along [100] or 2/b along [010]; or along <100>
c			None	c/2 along z-axis; or (a+b+c)/2 along [111] on rhombohedral axes
n	Diagonal glide plane			(a+b)/2 or (b+c)/2 or (c+a)/2; Or (a+b+c)/2 (tetragonal and cubic)
d	"Diamond" glide plane			(a±b)/4 or (b±c)/4 or (c±a)/4; Or (a±b±c)/4 (tetragonal and cubic) See Note #1

Note #1: In the "diamond" glide plane the glide translation is half of the resultant of the two possible axial glide translations. The arrow in the first diagram show the direction of the horizontal component if the translation when the z-component is positive. In the second diagram the arrow shows the actual direction of the glide translation; there is always another diamond-glide reflection plane parallel to the first with a height difference of 1/4 and the arrow pointing along the other diagonal of the cell face.

### Glide planes

---- translation plus reflection across the glide plane

\* axial glide plane (glide plane along axis)

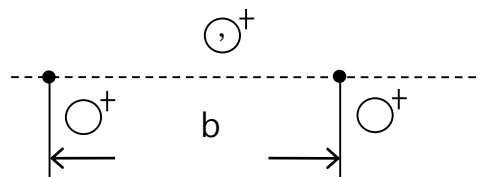
---- translation by half lattice repeat plus reflection

---- three types of axial glide plane

i. a glide, b glide, c glide (a, b, c)

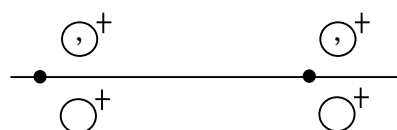
$\frac{1}{2}$  along line in plane  $\equiv$  ( $\frac{1}{2}$  along line parallel to projection plane)

e.g. b glide



--- graphic symbol for the axial glide plane along y axis

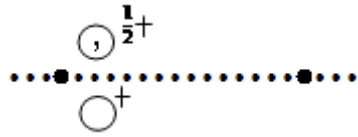
c.f. mirror (m)



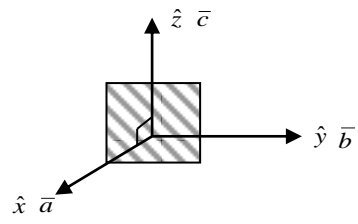
— graphic symbol for mirror

MS2041 lecture notes for educational purposes only

\*If the axial glide plane is  $\frac{1}{2}$  normal to projection plane, the graphic symbol change to

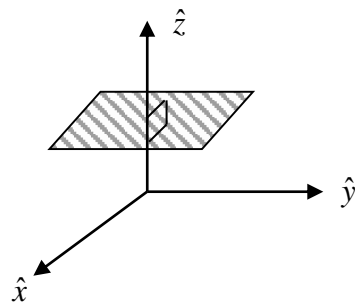


c glide

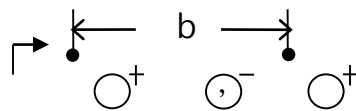


glide plane  $\perp$   $\hat{z}$  axis

\* If b glide plane is  $\perp \hat{z}$  axis,



glide plane symbol  $\dashv$



$\uparrow$   
underneath the glide plane

\* c glide  $\frac{c}{2}$  along z axis

or

$\frac{a+b+c}{2}$  along [111] on rhombohedral axis

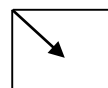
ii. **Diagonal glide (n)**

$\frac{a+b}{2}$  ,  $\frac{b+c}{2}$  ,  $\frac{a+c}{2}$  or  $\frac{a+b+c}{2}$  (tetragonal, cubic system)

If glide plane is perpendicular to the drawing plane (xy plane), the graphic symbol is



If glide plane is parallel to the drawing plane, the graphic symbol is























iii. **Diamond glide (d)**

$\frac{a+b}{4}$  or  $\frac{a+b+c}{4}$  (tetragonal, cubic system)



## B Symbols of symmetry axes

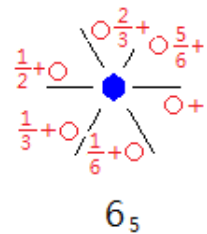
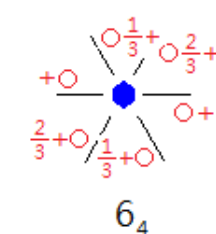
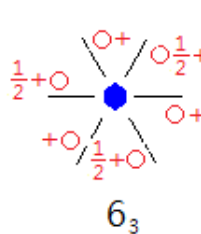
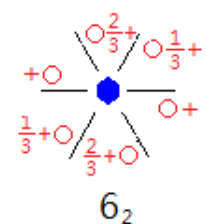
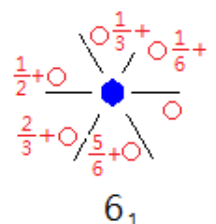
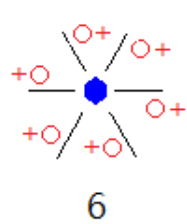
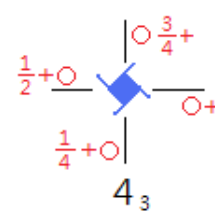
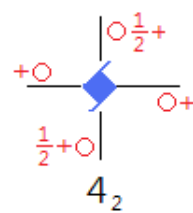
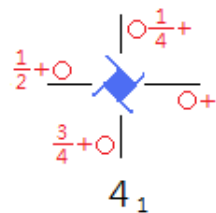
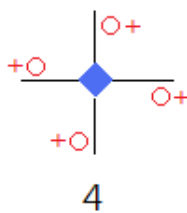
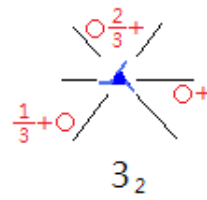
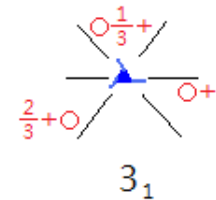
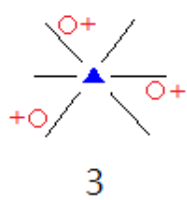
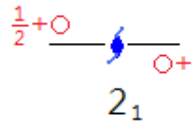
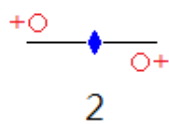
symbol	Symmetry axis	Graphic symbol	Nature of right-handed screw translation along the axis	symbol	Symmetry axis	Graphic symbol	Nature of right-handed screw translation along the axis
1	Rotation monad	none	none	4	Rotation tetrad		none
$\bar{1}$	Inversion monad		none	$4_1$	Screw tetrads		$c/4$
2	Rotation diad	 Normal to paper	none	$4_2$			$2c/4$
				$4_3$			$3c/4$
		 Parallel to paper		$\bar{4}$	Inversion tetrad		none
$2_1$	Screw diad	 Normal to paper	$c/2$ either $a/2$ or $c/2$	6	Rotation hexad		none
				$6_1$	Screw hexads		$c/6$
$6_2$		$2c/6$					
3	Rotation triad		none	$6_3$			$3c/6$
$3_1$	Screw triad	 	$c/3$ $2c/3$	$6_4$		$4c/6$	
$3_2$				$6_5$		$5c/6$	
$\bar{3}$	Inversion triad		none	$\bar{6}$	Inversion hexad		none

i All possible screw operations

\*screw axis --- translation  $\tau$  plus rotation

screw  $R_n$  along c axis

= counterclockwise rotation  $(360/R)^\circ$  + translation  $(n/R)\bar{c}$



MS2041 lecture notes for educational purposes only

Space group: 230

(1) Symmorphic space group is defined as a space group that may be specified entirely by symmetry operation acting at a common point (the operations need not involve  $\tau$ ) as well as the unit cell translation

\* 73 symmorphic space groups

Crystal system	Bravais lattice	Space group
Triclinic	p	P1, P $\bar{1}$
Monoclinic	P	P2, Pm, P2/m
	B or A	B2, Bm B2/m (1 <sup>st</sup> setting)
Orthorhombic	P	P222, Pmm2, Pmmm
	C, A or B	C222, Cmm2, Amm2*, Cmmm
	I	I222, Imm2, Immm
	F	F222, Fmm2, Fmmm
Tetragonal	P	P4, P $\bar{4}$ , P4/m, P4mm P $\bar{4}$ 2m, P $\bar{4}$ m2*, P4/mmm
	I	I4, I $\bar{4}$ , I4/m, I422, I4mm I $\bar{4}$ 2m, I $\bar{4}$ m2*, I4/mmm
Cubic	P	P23, Pm3, P432, P $\bar{4}$ 3m, Pm3m
	I	I23, Im3, I432, I $\bar{4}$ 3m, Im3m
	F	F23, Fm3, F432, F $\bar{4}$ 3m, Fm3m
Trigonal	P	P3, P $\bar{3}$ , P312, P321*, P3m1 P31m*, P $\bar{3}$ 1m, P $\bar{3}$ m1*
(Rhombohedral)	R	R3, R $\bar{3}$ , R32, R3m, R $\bar{3}$ m
Hexagonal	P	P6, P $\bar{6}$ , P6/m, P622, P6mm
		P $\bar{6}$ m2, P $\bar{6}$ 2m*, P6/mmm

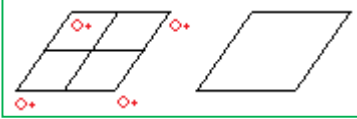
(2) Nonsymmorphic space group is defined as a space group involving at least a translation  $\tau$

MS2041 lecture notes for educational purposes only

Examples

(All the space groups in the following pages are adapted from the International Tables for Crystallography and replotted in the color form for educational purposes.)

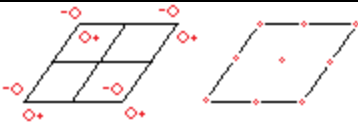
Space group P1

P1 $C_1^1$		No. 1	P1	1 Triclinic
				
			Origin on 1	
Number of positions	Wyckoff notation	Point symmetry	Coordinates of equivalent positions	Condition limiting possible reflections
1	a	1	x, y, z	No conditions



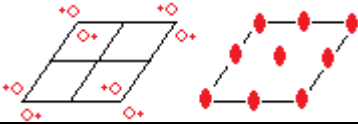
MS2041 lecture notes for educational purposes only

Space group  $P\bar{1}$

$P\bar{1}$ $C_1^1$		No. 2	$P\bar{1}$	$\bar{1}$ Triclinic
				
			Origin on $\bar{1}$	
Number of positions	Wyckoff notation	Point symmetry	Coordinates of equivalent positions	Condition limiting possible reflections
2	i	1	$x, y, z ; \bar{x}, \bar{y}, \bar{z}$	General: No conditions
1	h	$\bar{1}$	$\frac{1}{2}, \frac{1}{2}, \frac{1}{2}$	Special: No conditions
1	g	$\bar{1}$	$0, \frac{1}{2}, \frac{1}{2}$	
1	f	$\bar{1}$	$\frac{1}{2}, 0, \frac{1}{2}$	
1	e	$\bar{1}$	$\frac{1}{2}, \frac{1}{2}, 0$	
1	d	$\bar{1}$	$\frac{1}{2}, 0, 0$	
1	c	$\bar{1}$	$0, \frac{1}{2}, 0$	
1	b	$\bar{1}$	$0, 0, \frac{1}{2}$	
1	a	$\bar{1}$	$0, 0, 0$	

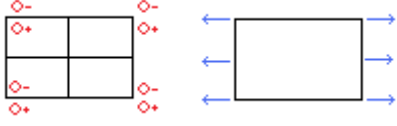
MS2041 lecture notes for educational purposes only

Space group P112

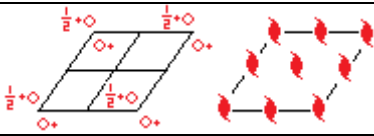
P112 $C_2^1$		No. 3	P112	2 Monoclinic
				
Ist setting			Origin on 2; unique axis c	
Number of positions	Wyckoff notation	Point symmetry	Coordinates of equivalent positions	Condition limiting possible reflections
2	e	1	$x, y, z; \bar{x}, \bar{y}, z$	General: $\begin{Bmatrix} hkl \\ hk0 \\ 00l \end{Bmatrix}$ No conditions
1	d	2	$\frac{1}{2}, \frac{1}{2}, z$	Special: No conditions
1	c	2	$\frac{1}{2}, 0, z$	
1	b	2	$0, \frac{1}{2}, z$	
1	a	2	$0, 0, z$	

MS2041 lecture notes for educational purposes only

Space group P121

P121 $C_2^1$		No. 3	P121	2 Monoclinic
				
			Origin on 2; unique axis b	2 <sup>nd</sup> setting
Number of positions	Wyckoff notation	Point symmetry	Coordinates of equivalent positions	Condition limiting possible reflections
2	e	1	$x, y, z; \bar{x}, y, \bar{z}$	General: $\begin{cases} hkl \\ h0l \\ 0k0 \end{cases}$ No conditions
1	d	2	$\frac{1}{2}, y, \frac{1}{2}$	Special: No conditions
1	c	2	$\frac{1}{2}, y, 0$	
1	b	2	$0, y, \frac{1}{2}$	
1	a	2	$0, y, 0$	

Space group P112<sub>1</sub>

P2 <sub>1</sub> C <sub>2</sub> <sup>2</sup>		No. 4	P112 <sub>1</sub>	2 Monoclinic
				
Ist setting			Origin on 2 <sub>1</sub> ; unique axis c	
Number of positions	Wyckoff notation	Point symmetry	Coordinates of equivalent positions	Condition limiting possible reflections
2	a	1	$x, y, z; \bar{x}, \bar{y}, \frac{1}{2} + z$	General: hkl: No conditions hk0: No conditions 00l: l=2n

Explanation:

#1 Consider the diffraction condition from plane (h k 0)

Two atoms at  $x, y, z; \bar{x}, \bar{y}, \frac{1}{2} + z$

The diffraction amplitude F can be expressed as

$$\begin{aligned}
 F &= \sum_i f_i * e^{-2\pi i[h k l]*[x y z]} \\
 &= \sum_i f_i * e^{-2\pi i[h k 0]*[x y z]} \\
 &= f_i * e^{-2\pi i[h k 0]*[x y z]} + f_i * e^{-2\pi i[h k 0]*[\bar{x} \bar{y} 1/2 + z]} \\
 &= f_i * e^{-2\pi i(hx+ky)} + f_i * e^{-2\pi i(-hx-ky)} \\
 &= f_i * (e^{-2\pi i(hx+ky)} + e^{2\pi i(hx+ky)}) \\
 &= f_i * (2 \cos(2\pi i(hx + ky))) \\
 &= 2f_i
 \end{aligned}$$

Therefore, no conditions can limit the (h, k, 0) diffraction.

MS2041 lecture notes for educational purposes only

#2 For the planes (00l)

Two atoms at  $x, y, z$ ;  $\bar{x}, \bar{y}, \frac{1}{2}+z$

The diffraction amplitude  $F$  can be expressed as

$$\begin{aligned} F &= \sum_i f_i * e^{-2\pi i[h k l]*[x_i y_i z_i]} \\ &= \sum_i f_i * e^{-2\pi i[0 0 l]*[x_i y_i z_i]} \\ &= f_i * e^{-2\pi i[0 0 l]*[x y z]} + f_i * e^{-2\pi i[0 0 l]*[\bar{x} \bar{y} 1/2 + z]} \\ &= f_i * e^{-2\pi i l z} + f_i * e^{-2\pi i(\frac{1}{2} + l z)} \\ &= f_i * e^{-2\pi i l z} * (1 + e^{-\pi i l}) \\ &= f_i * (1 + e^{-\pi i l}) \end{aligned}$$

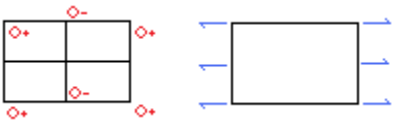
If  $l=2n$ , then  $F=2f_i$

If  $l=2n+1$ , then  $F=0$

Therefore, the condition  $l=2n$  limit the  $(0, 0, l)$  diffraction.

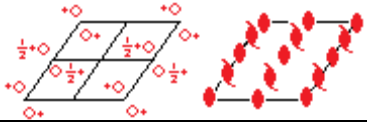
MS2041 lecture notes for educational purposes only

Space group P12<sub>1</sub>1

P2 <sub>1</sub> C <sub>2</sub> <sup>2</sup>		No. 4	P12 <sub>1</sub> 1	2 Monoclinic
				
			Origin on 2 <sub>1</sub> ; unique axis b	2 <sup>nd</sup> setting
Number of positions	Wyckoff notation	Point symmetry	Coordinates of equivalent positions	Condition limiting possible reflections
2	a	1	$x, y, z; \bar{x}, \frac{1}{2}+y, \bar{z}$	General: hkl: No conditions h0l: No conditions 0k0: k=2n

MS2041 lecture notes for educational purposes only

Space group B112

B2 $C_2$		No. 5	B112	2 Monoclinic
				
Ist setting			Origin on 2; unique axis c	
Number of positions	Wyckoff notation	Point symmetry	Coordinates of equivalent positions	Condition limiting possible reflections
4	c	1	$x, y, z; \bar{x}, \bar{y}, z$	General: $hkl: h+l=2n$ $hk0: h=2n$ $00l: l=2n$
2	b	2	$0, \frac{1}{2}, z$	Special: as above only
2	a	2	$0, 0, z$	

MS2041 lecture notes for educational purposes only

Space group P 4/m  $\bar{3}$  2/m

Pm3m $O_h^h$		No. 221	P 4/m $\bar{3}$ 2/m	m3m Cubic
Ist setting			Origin at centre; m3m	
Number of positions	Wyckoff notation	Point symmetry	Coordinates of equivalent positions	Condition limiting possible reflections
48	n	1	$x,y,z; z,x,y; y,z,x; x,z,y; y,x,z; z,y,x;$ $x, \bar{y}, z; z, \bar{x}, y; y, \bar{z}, x; x, \bar{z}, \bar{y}; y, \bar{x}, \bar{z}; z, \bar{y}, \bar{x};$ $\bar{x}, y, \bar{z}; \bar{z}, x, \bar{y}; \bar{y}, z, \bar{x}; \bar{x}, z, \bar{y}; \bar{y}, x, \bar{z}; \bar{z}, y, \bar{x};$ $\bar{x}, \bar{y}, z; \bar{z}, \bar{x}, y; \bar{y}, \bar{z}, x; \bar{x}, \bar{z}, \bar{y}; \bar{y}, \bar{x}, \bar{z}; \bar{z}, \bar{y}, \bar{x};$ $\bar{x}, y, z; \bar{z}, x, y; \bar{y}, z, x; \bar{x}, z, y; \bar{y}, x, z; \bar{z}, y, x;$ $x, \bar{y}, z; z, \bar{x}, y; y, \bar{z}, x; x, \bar{z}, \bar{y}; y, \bar{x}, \bar{z}; z, \bar{y}, \bar{x};$ $x, y, \bar{z}; z, x, \bar{y}; y, z, \bar{x}; x, z, \bar{y}; y, x, \bar{z}; z, y, \bar{x};$	General: $\left. \begin{matrix} (hkl) \\ (hhl) \\ (0kl) \end{matrix} \right\} \text{No conditions}$
24	m	M	$x,x,z; z,x,x; x,z,x; \bar{x}, \bar{x}, \bar{z}; \bar{z}, \bar{x}, \bar{x}; \bar{x}, \bar{z}, \bar{x};$ $x, \bar{x}, z; z, \bar{x}, \bar{x}; x, \bar{z}, \bar{x}; \bar{x}, x, z; \bar{z}, x, x; \bar{x}, z, x;$ $\bar{x}, x, z; \bar{z}, \bar{x}, \bar{x}; \bar{x}, z, \bar{x}; x, \bar{x}, z; z, \bar{x}, x; x, \bar{z}, x;$ $\bar{x}, \bar{x}, z; \bar{z}, \bar{x}, x; \bar{x}, \bar{z}, x; x, x, \bar{z}; z, x, \bar{x}; \bar{x}, z, \bar{x};$	Special: No conditions
24	l	M	$\frac{1}{2}y,z; z, \frac{1}{2}y; y, z, \frac{1}{2}; \frac{1}{2}z,y; y, \frac{1}{2}z; z,y, \frac{1}{2};$ $\frac{1}{2}\bar{y}, \bar{z}; \bar{z}, \frac{1}{2}\bar{y}; \bar{y}, \bar{z}, \frac{1}{2}; \frac{1}{2}\bar{z}, \bar{y}; \frac{1}{2}\bar{y}, \bar{z}; \bar{z}, \bar{y}, \frac{1}{2};$ $\frac{1}{2}y, \bar{z}; \bar{z}, \frac{1}{2}y; y, \bar{z}, \frac{1}{2}; \frac{1}{2}\bar{z}, y; y, \frac{1}{2}\bar{z}; \bar{z}, y, \frac{1}{2};$ $\frac{1}{2}\bar{y}, z; z, \frac{1}{2}\bar{y}; \bar{y}, z, \frac{1}{2}; \frac{1}{2}z, \bar{y}; \bar{y}, \frac{1}{2}z; z, \bar{y}, \frac{1}{2};$	
24	k	M	$0,y,z; z,0,y; y,z,0; 0,z,y; y,0,z; z,y,0;$ $0,\bar{y}, \bar{z}; \bar{z}, 0,\bar{y}; \bar{y}, \bar{z}, 0; 0,\bar{z}, \bar{y}; 0, \bar{y}, 0, \bar{z}; \bar{z}, \bar{y}, 0;$ $0,y, \bar{z}; \bar{z}, 0,y; y, \bar{z}, 0; 0,\bar{z}, y; y, 0, \bar{z}; \bar{z}, y, 0;$ $0,\bar{y}, z; z, 0,\bar{y}; \bar{y}, z, 0; 0,z, \bar{y}; \bar{y}, 0, z; z, \bar{y}, 0;$	
12	j	mm	$\frac{1}{2}, x, x; x, \frac{1}{2}, x; x, x, \frac{1}{2}; \frac{1}{2}, x, \bar{x}; \bar{x}, \frac{1}{2}, x; x, \bar{x}, \frac{1}{2};$ $\frac{1}{2}, \bar{x}, \bar{x}; \bar{x}, \frac{1}{2}, \bar{x}; \bar{x}, \bar{x}, \frac{1}{2}; \frac{1}{2}, \bar{x}, x; x, \frac{1}{2}, \bar{x}; \bar{x}, x, \frac{1}{2};$	
12	i	mm	$0,x,x; x,0,x; x,x,0; 0,x, \bar{x}; \bar{x}, 0,x; x, \bar{x}, 0;$ $0, \bar{x}, \bar{x}; \bar{x}, 0, \bar{x}; \bar{x}, \bar{x}, 0; 0,\bar{x},x; x, 0, \bar{x}; \bar{x}, x, 0;$	
12	h	mm	$x, \frac{1}{2}, 0; 0, x, \frac{1}{2}; \frac{1}{2}, 0, x; x, 0, \frac{1}{2}; \frac{1}{2}, x, 0; 0, \frac{1}{2}, x;$ $\bar{x}, \frac{1}{2}, 0; 0, \bar{x}, \frac{1}{2}; \frac{1}{2}, 0, \bar{x}; \bar{x}, 0, \frac{1}{2}; \frac{1}{2}, \bar{x}, 0; 0, \frac{1}{2}, \bar{x}$	
8	g	3m	$x,x,x; x,\bar{x},\bar{x}; \bar{x},x,\bar{x}; \bar{x},\bar{x},x;$ $\bar{x},\bar{x},\bar{x}; \bar{x},x,x; x,\bar{x},x; x,x,\bar{x}$	
6	f	4mm	$x, \frac{1}{2}, \frac{1}{2}; \frac{1}{2}, x, \frac{1}{2}; \frac{1}{2}, \frac{1}{2}, x; \bar{x}, \frac{1}{2}, \frac{1}{2}; \frac{1}{2}, \bar{x}, \frac{1}{2};$ $\bar{x}, \frac{1}{2}, \frac{1}{2}; \frac{1}{2}, \bar{x}, \frac{1}{2}; \frac{1}{2}, \frac{1}{2}, \bar{x}$	
6	e	4mm	$x, 0, 0; 0, x, 0; 0, 0, x;$ $\bar{x}, 0, 0; 0, \bar{x}, 0; 0, 0, \bar{x}$	
3	d	4/mmm	$\frac{1}{2}, 0, 0; 0, \frac{1}{2}, 0; 0, 0, \frac{1}{2}$	
3	c	4/mmm	$0, \frac{1}{2}, \frac{1}{2}; \frac{1}{2}, 0, \frac{1}{2}; \frac{1}{2}, \frac{1}{2}, 0$	
1	b	m3m	$\frac{1}{2}, \frac{1}{2}, \frac{1}{2}$	
1	a	m3m	0,0,0	

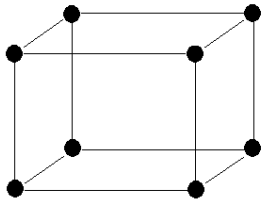


MS2041 lecture notes for educational purposes only

The usage of space group for crystal structure identification

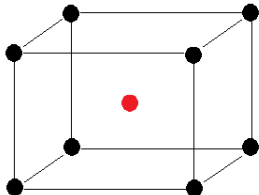
Space group  $P 4/m \bar{3} 2/m$

#1 Simple cubic



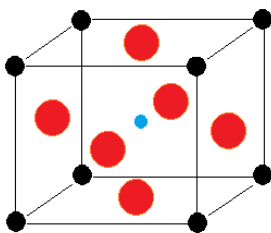
Number of positions	Wyckoff notation	Point symmetry	Coordinates of equivalent positions
1	A	m3m	0, 0, 0

#2 CsCl structure



atoms	Number of positions	Wyckoff notation	Point symmetry	Coordinates of equivalent positions
Cl	1	a	m3m	0, 0, 0
Cs	1	b	m3m	$\frac{1}{2}, \frac{1}{2}, \frac{1}{2}$

#3 BaTiO<sub>3</sub> structure



atoms	Number of positions	Wyckoff notation	Point symmetry	Coordinates of equivalent positions
Ba	1	a	m3m	0, 0, 0
Ti	1	b	m3m	$\frac{1}{2}, \frac{1}{2}, \frac{1}{2}$
O	3	c	4/mmm	$0, \frac{1}{2}, \frac{1}{2}$ $\frac{1}{2}, 0, \frac{1}{2}$ $\frac{1}{2}, \frac{1}{2}, 0$